

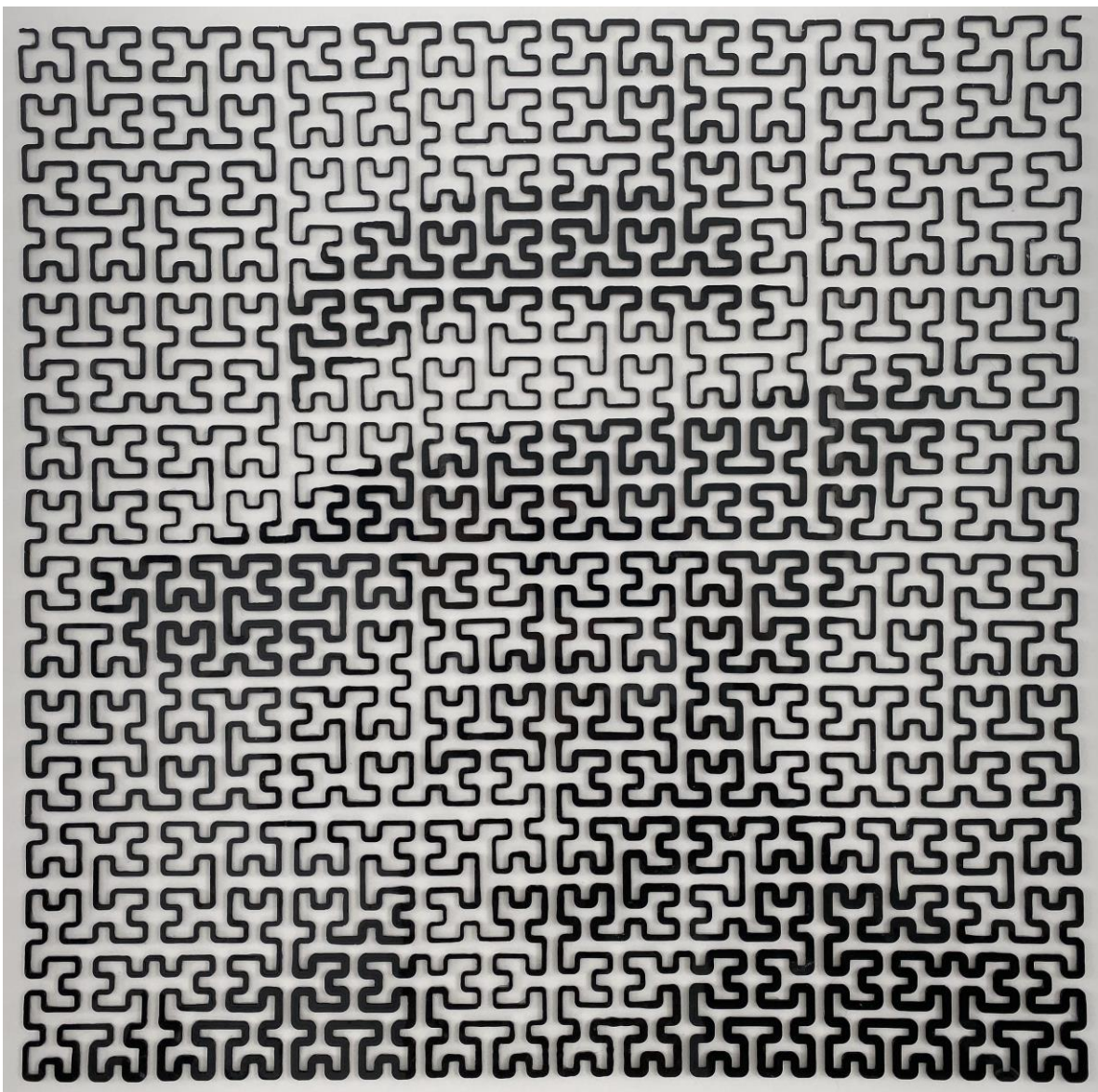
## Hilbert's Portrait via his Space-Filling Curve

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### Abstract

This paper reports on how I created a 3D-printed portrait of the mathematician David Hilbert using the sixth iterate of Hilbert's space-filling curve. I render the portrait by varying the thickness of sequential segments of Hilbert's curve according to the grayscale pixel values of a well-known photo of him.



**Figure 1:** *Hilbert's image is embedded within his famous space-filling curve.*

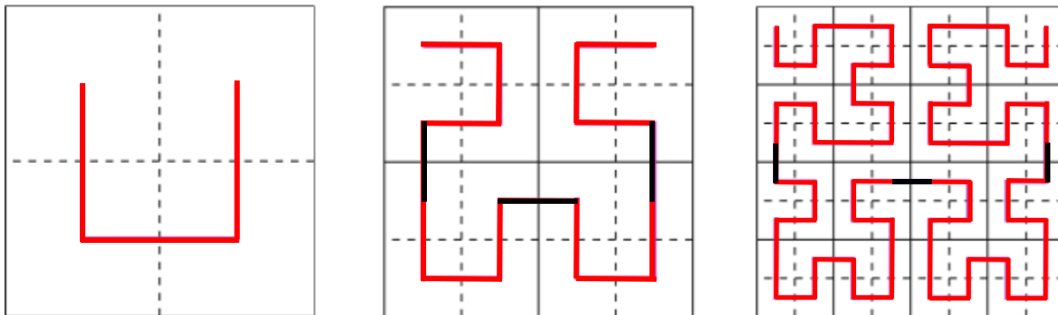
## Introduction

David Hilbert (1862–1943) was a German mathematician who was undoubtedly the most famous mathematician of his day. Known for the 23 problems he presented at the International Congress of Mathematics in Paris in 1900, he influenced the trajectory of mathematics in the decades to follow. A gifted leader, Hilbert was in a good position to define the future of mathematics because he was well-versed in a wide range of mathematical fields, having made highly original contributions to logic, geometry, analysis and algebra. His impact is apparent to us today by the numerous mathematical objects and theorems that now bear his name: Hilbert axioms, Hilbert space, Hilbert’s Finite Basis Theorem, and Hilbert’s curve, to name a few.

In this paper I present a portrait I created of David Hilbert using his well-known space-filling curve and a 3D printer. (See Figure 1.) The portrait serves as an homage to Hilbert, but it also illustrates the human brain’s remarkable ability to fill in missing information as it works to make sense of the data received from the surrounding world. While viewing the portrait, the reader is encouraged to experiment by squinting and varying the viewing distance. Unlike most images, this one becomes clearer when moved further away.

### Hilbert’s Space-Filling Curve

In 1879 German mathematician Eugen Netto proved that every bijective map from the unit interval  $[0,1]$  to the unit square  $[0,1]^2$  is necessarily discontinuous, and mathematicians naturally became interested in the possible existence of a continuous surjective map from  $[0,1]$  to  $[0,1]^2$ . It took over a decade for Italian mathematician Giuseppe Peano to answer this question in the affirmative; he provided the first example of a space-filling curve in 1890. Hilbert conceived of his well-known curve a year later. (See [1] and [5] for a more thorough coverage of the rich mathematics discussed briefly here.) Today Hilbert’s space-filling curve is the better known of the two, probably because Hilbert introduced his construction geometrically, making it easier to imagine. As Figure 2 illustrates, Hilbert constructed his curve recursively.



**Figure 2:** Hilbert’s curve is defined recursively, starting with the fundamental configuration “U” and replacing the four subsquares of each iteration with an appropriately rotated copy of the previous iteration.

Starting with the seed configuration “U” in the unit square, each iterate of Hilbert’s curve is constructed from the previous one by subdividing the square into four subsquares and applying the following rules:

- Rotate the previous iteration 90 degrees counterclockwise and place it in the upper left subsquare
- Rotate the previous iteration 90 degrees clockwise and place it in the upper right subsquare
- Retaining their original orientation, place a copy of the previous iteration in each of the two bottom subsquares.
- Finally, add three connecting line segments to ensure the resulting curve is continuous.

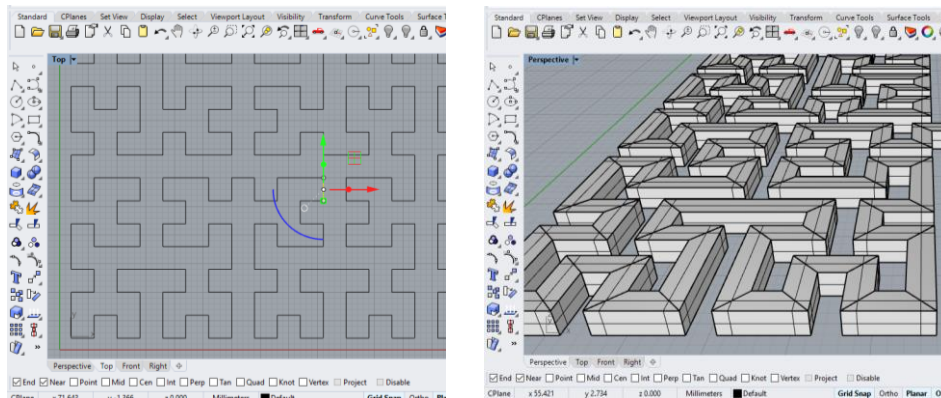
Of course, Hilbert’s curve is a theoretical object, achieved by applying the iterative process ad infinitum. Figure 4 below depicts a 3D print of the fifth iteration of Hilbert’s curve, and Hilbert’s portrait was generated with the sixth iteration.

### A Three-Phase Process

I created the portrait in the fall of 2019 while I was on sabbatical at the Institute of Computational and Experimental Research in Mathematics (ICERM) at Brown University, participating in their special semester on “Illustrating Mathematics.” Using Python scripts within the 3D modeling program Rhinoceros (or “Rhino”), my code reads in an image and uses pixel data to generate a rectangular piping along the curve. The width of the rectangular profile of the piping at a point depends on the intensity of the pixel at that point; it is wider when the intensity of the pixel is lower (where the image is darker) and thinner when the intensity of the pixel is higher (where the image is brighter). I chose this project with both the end product and the creation process in mind because two of my sabbatical goals were 1) to become more proficient programming in Python and 2) to learn how to design and print 3D mathematical objects. I broke up the creation process into three phases.

#### *Phase 1 – Generate square piping along the Hilbert Curve*

Within Rhino is a “SweepOneRail” class, which makes it easy to render a surface generated by sweeping cross-section curves along a single rail curve. One simply draws a curve in the plane, defines the profile shape of the (uniform) cross-section, and clicks the “SweepOneRail” button in the menu. I chose to take a more complicated approach in generating the square piping along Hilbert’s curve, however, because ultimately I would need to generate piping having nonuniform cross sections (that is, rectangles of varying dimensions), and I would need to sweep the piping along thousands of curve segments. So in preparation for phase 2, I wrote a Python script to automate the piping process. The program generates square piping along a collection of curves selected by the user. Figure 3 (left) shows an image of a portion of the fourth iterate of Hilbert’s curve constructed in Rhino out of 1,023 tiny line segments. Alongside side it (Figure 3, right) is the piped curve rendered in Rhino. (After drawing the first iterate of Hilbert’s curve in Rhino, the software’s copy, paste and rotate commands make it easy to reproduce what the production rules would do to create higher iterates.)

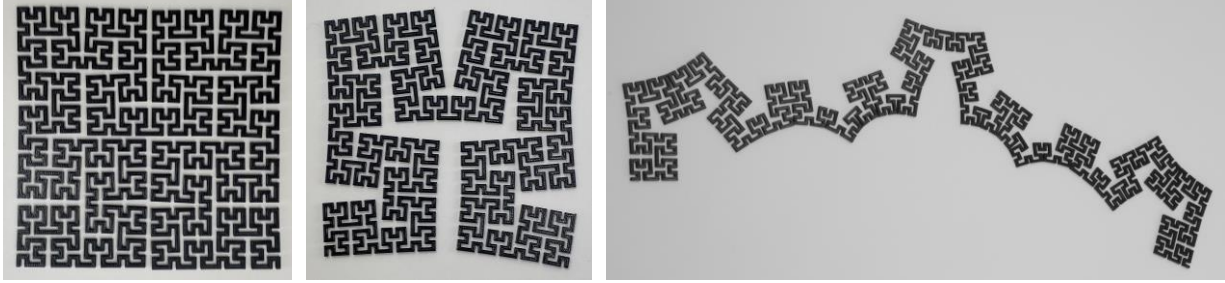


**Figure 3:** (left) Hilbert’s curve rendered in Rhino with 1023 line segments and (right) the square piping rendered in Rhino using a Python script

Figure 4 (top left) shows the finished 3D printed product. The piping was printed with flexible Thermoplastic Polyurethane (TPU) filament, which allows one not only to touch the curve, but also to stretch it and experience its local structure.

So how did Hilbert conceive of his famous curve? As he himself described, his intuition was based on the realization that if the interval  $[0, 1]$  were to be mapped to the unit square continuously, then each of the four subintervals  $[0, 1/4]$ ,  $[1/4, 1/2]$ ,  $[1/2, 3/4]$ , and  $[3/4, 1]$  should be mapped to one of four subsquares partitioning the unit square, with adjacent subintervals corresponding to adjacent subsquares [3]. This “subsquare” structure is readily visible in the 3D print depicted in the middle image of Figure 4.





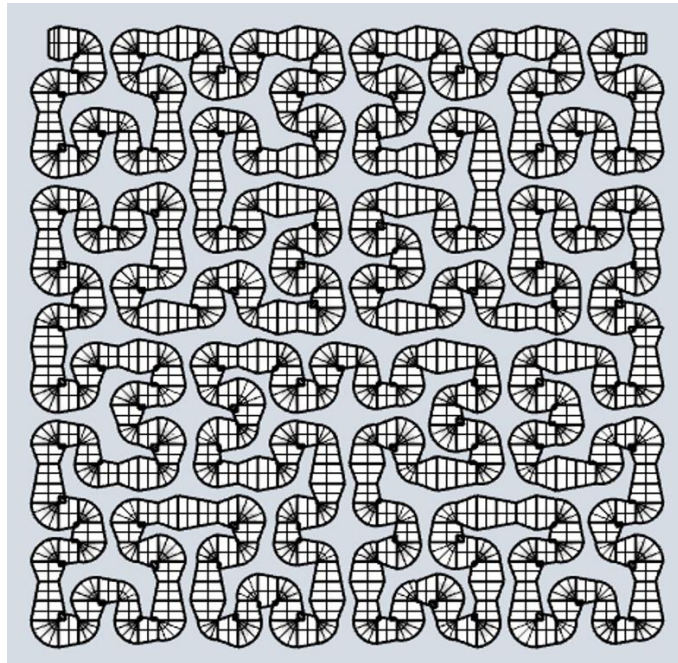
**Figure 4:** *Stretching the piped Hilbert curve 3D printed in the more flexible Thermoplastic Polyurethane (TPU) filament reveals local structure of the curve.*

**Phase 2 – Adapt the Python script to allow for rectangular piping with variable width**

In this next phase of the project, I constructed iterates of Hilbert’s curve using circular arcs at the curve’s corners to smooth out the corners of the piping. Adapting the script used to create the square piping in Phase 1, I generated rectangular piping with varying width by incorporating Rhino’s “GlobalShapeBlending” property. Given a rectangle defining the cross section of the pipe at the start of a rail curve and a second rectangle (of different dimensions) defining the cross section at the end of the same curve, the “GlobalShapeBlending” property allows one to create a pipe having cross sections with dimensions that vary linearly between the two rectangles. To test my code (which, again, automates the piping process on a selected collection of curves), I generated rectangular piping on 600+ tiny line segments and circular arcs making up the fourth iterate of Hilbert’s curve, defining the dimensions  $w$  (width) and  $h$  (height) of the rectangular cross sections at the endpoints  $(x, y)$  of each of the curve segments by:

$$\begin{aligned} w(x, y) &= 2 + 1.4 ([x + y] \bmod 3) \\ h(x, y) &= 2 \end{aligned}$$

(The origin is at the bottom left-hand corner, and  $[x + y]$  denotes the floor function applied to  $x + y$ .) The top down view of the resulting surface mesh rendered by Rhino is surprisingly appealing!



**Figure 5:** *The mesh generated by Rhino produced “Hilbert’s Intestines.”*

**Phase 3 – Incorporate Python script to read in pixel data from an image**

In the final phase of this project I created Hilbert's portrait using the sixth iterate of his curve by adapting the script from Phase 2 so that it could read in pixel data from a given image. I constructed the portrait in pieces by rendering 16 “subsquares” in Rhino and then printing them on an Ultimaker 3. Similar to the piping that generated “Hilbert's Intestines,” the width of the piping along each tiny curve segment of a given subsquare varied linearly along the curve between the starting and ending rectangular cross sections.

In rendering Hilbert's portrait, the dimensions,  $w$  and  $h$ , of the rectangular cross section at  $(x, y)$  depended on the pixel data of the underlying photograph of Hilbert. Because the piped curve would be printed ultimately in black filament and placed on a white background, darker areas in the photograph correspond to wider rectangular piping. The rectangular cross sections are thinner wherever the photo is lighter. I used the Rhino plug-in “Rhinoscript” to access image data. The “GetPixel” command gets the color of a pixel and “GetBrightness” computes its intensity. The height of the piping remained fixed throughout.

This was a time-consuming endeavor, requiring between 45 to 100 minutes of printing time for each of the 16 sub-squares (see Figure 6), and there were many failed attempts with clogged printer heads and broken filaments. Each printed subsquare is approximately 5 inches in width, so the entire portrait is approximately  $20 \times 20$  inches. I glued the 16 successful fourth iterate prints onto white foam board to create the final portrait. (See Figure 7 for close-up views.)

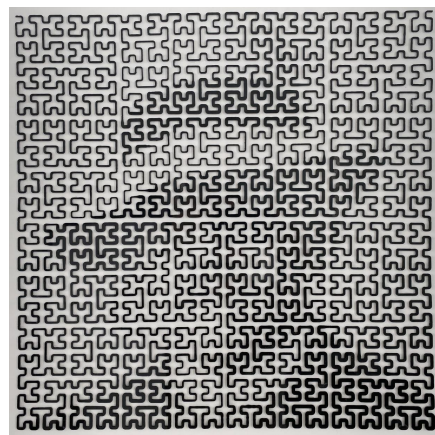


**Figure 6:** One of the sixteen subsquares printing on an Ultimaker 3

Of course, the final result is necessarily of low dimension because of the lengthy printing time. However, I did experiment within Rhino, generating Hilbert's portrait using the seventh iterate of the space-filling curve. The portrait's precision increases with the use of higher iterates. (In fact, higher iterates almost look *too much* like the original photograph. I appreciate the ambiguity of the current version.) Additionally, precision within a fixed iterate increases when scaling down the image. The thumbnail of Figure 1 provided in Figure 8 below illustrates this phenomenon. In this smaller, scaled-down version, Hilbert's mustache is now visible—and maybe even a hint of his glasses.



**Figure 7:** Close-ups reveal the curve's varying width and its three-dimensional nature.



**Figure 8:** Scaling down the portrait in Figure 1 seems to improve precision.

## Related Work and Future Directions

Creating a portrait out of a single path is not new. Bob Bosch created a number of them using the path of a traveling salesman visiting dots (or cities) in a rectangular region; he starts with a collection of dots distributed to have a density reflecting the shadows and highlights of a given source image. (See Chapter 6 of [2] for three famous Hamiltons rendered with Hamiltonian paths as well as a beautiful portrait of the Mona Lisa.) My approach differs from Bosch's in that my path is a space-filling curve, and I capture the lights and darks of Hilbert's image by varying the path's width. In 2000, Ken Knowlton also used a space-filling curve to render the portrait of its creator, Doug McKenna. (See "Portrait with a Single Line" [6, p. 171].) Like Bosch, Knowlton used a path with a fixed width. Printing the curve in white on a black background, Knowlton captured McKenna's likeness by using denser, higher iterates of the space-filling curve in lighter regions of the source image and lower iterates in the darker regions. So, unlike Bosch, Knowlton captured the lights and darks in McKenna's portrait by capitalizing on the path's self-similarity. My approach differs from Knowlton's in that I vary the width of a *single iterate* of a space-filling curve; my approach captures Hilbert's likeness by capitalizing on the space-filling property of the path.

My rendering of Hilbert is also reminiscent of the portraits produced by Ken Knowlton, Bob Bosch and Robert Silver using photomosaics. In *photographic mosaics* or *photomosaics*, a source image is divided into an array of rectangular regions, each of which is replaced with either some form of physical mosaic material (e.g., stones, shells, dice or dominoes [2,4]), or with other photographs that match the pixel data of the target image within that region (as in Robert Silver's work [7]). The rectangular regions in the source image are often matched with a finite set of mosaic materials (e.g., two full sets of Dominoes or a library of photographs), and the resulting portrait often resembles a collage which becomes clearer as the viewing distance increases. Similar to the photomosaics approach, the width of my piping is determined by reading in local pixel data. However, my rendering of Hilbert does not have the look of a collage as it is created with one single path.

In this project, the height of the rectangular piping remained fixed throughout the entirety of the space-filling curve, but I intend to experiment in varying both the height and the width in future work. I also want to make use of other types of space-filling curves to render future images. There are many possibilities!

## Acknowledgements

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